FEW-SHOT MALWARE DETECTION USING A NOVEL ADVERSARIAL REPROGRAMMING MODEL

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### by

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I HEREBY RECOMMEND THAT THE THESIS PREPARED UNDER MY SUPER-

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ABSTRACT

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The increasing sophistication of malware has made detecting and defending against new strains a major challenge for cybersecurity. One promising approach to this problem is using machine learning techniques that extract representative features and train clas- sification models to detect malware in an early stage. However, training such machine learning-based malware detection models represents a significant challenge that requires a large number of high-quality labeled data samples while it is very costly to obtain them in real-world scenarios. In other words, training machine learning models for malware de- tection requires the capability to learn from only a few labeled examples. To address this challenge, in this thesis, we propose a novel adversarial reprogramming model for few-shot malware detection. Our model is based on the idea to re-purpose high-performance Ima- geNet classification model to perform malware detection using the features of malicious and benign files. We first embed the features of software files and a small perturbation to a host image chosen randomly from ImageNet, and then create an image dataset to train and test the model; after that, the model transforms the output into malware and benign classes. We evaluate the effectiveness of our model on a dataset of real-world malware and show that it significantly outperforms baseline few-shot learning methods. Additionally, we evaluate the impact of different pre-trained models, different data sizes, and different parameter values. Overall, our results suggest that the proposed adversarial reprogramming model is a promising direction for improving few-shot malware detection.

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**Introduction**

In this thesis, we would like to propose a machine learning solution to detect malware from a more practical yet challenging perspective where the labeled data samples are limited, which is called few-shot malware detection. In this chapter, we first describe the back- ground of malware and its detection, and our motivation for the proposed solution. After that, we specify our contribution and the organization of this thesis.

# Background

Malware, short for malicious software, is any software that is designed to harm or ex- ploit computer systems [[24](#_bookmark72)]. There are many different types of malware including viruses, worms, trojan horses, ransomware, and spyware. According to a recent report, which is illustrated in Figure [1.1](#_bookmark2), the total amount of malware as per recent findings surpassed 1.2 billion in 2022 [[3](#_bookmark51)]. The threat of malware is constantly evolving as criminals come up with new ways to gain access to systems and steal data. As more businesses move their operations to the cloud, the importance of protecting their data has never been greater. By identifying and removing malicious software before it can cause damage, you reduce the risk of your computer or network is compromised and the data within it being lost. This is the reason why malware detection is an important part of any security strategy. Different malware detection systems have been constantly designed and developed to ensure they

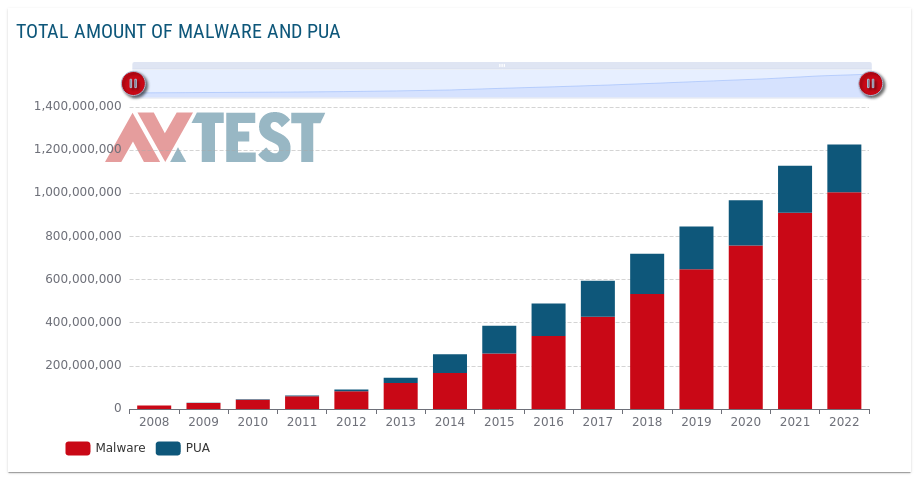


Figure 1.1: Statistics of malware over the years [[3](#_bookmark51)]

can detect threats and provide businesses with protection [[5](#_bookmark53)].

With the rapid development in machine learning, and especially the revolutionary learning structures and capabilities raised by deep learning [[29](#_bookmark77)], in recent years, the se- curity industry and researchers have developed different these data-driven algorithms and frameworks into practical products and applications for more accurate malware detection, which improve the protection of computer systems against attacks. Here, we discuss some of the advantages of using machine learning to detect malware.

One of the first advantages of machine learning in malware detection is that it provides accuracy in identifying new and unknown threats. Unlike traditional malware detection methods that rely on pre-defined rules to identify known threats, machine learning algo- rithms can recognize previously unseen malware patterns. By analyzing large numbers of samples obtained from real malware infections, machine learning models can learn which features of a file or program are most indicative of malicious behavior [[30](#_bookmark78)]. Once trained, these models can then be used to automatically analyze new samples and detect previously unknown threats.

Another advantage of using machine learning for malware detection is that it has the

potential to scale to large datasets. Since machine learning algorithms are based on algo- rithms that can learn from data, they can incorporate features from a large set of malicious samples and train a model to identify similar features in new samples. Thus, they can han- dle large quantities of data and can effectively detect a wide range of malicious files without the need for extensive manual analysis [[19](#_bookmark67), [42](#_bookmark90)]. For example, deep learning models can produce highly accurate results even for complicated datasets containing thousands of fea- tures. This makes them particularly suitable for addressing large-scale malware detection and classification problems.

Utilizing machine learning for detecting malware can also enhance system security with minimal human input, providing an additional benefit. As machine learning models are trained on real-world samples rather than on rule-based specifications, they can detect previously unknown threats based on features extracted from actual malware code.

Even though using machine learning for malware detection has a lot of advantages, there are downsides to using machine learning for malware detection. The most significant one of them is the requirement for labeled data samples. Labeled data is the heart of machine learning. The data that is fed into the machine learning model should fit the algorithm and needs to be sufficiently large for the model to train correctly [[53](#_bookmark101)], such that the model can capture the feature patterns and accordingly improve its learning and detection ability. Unfortunately, collecting such a large number of high-quality labeled malware samples is extremely difficult, and labeling the malware samples is also costly [[34](#_bookmark82), [19](#_bookmark67), [5](#_bookmark53)].

# Motivation

Based on the above discussions, we can summarize the challenge to use machine learning for malware detection is that we need to collect a large number of labeled data samples to facilitate model training. However, different from more straightforward annotations on

less complex data such as images, labeling malware data calls for solid domain knowledge and elaborate verification, which is time-consuming and labor-intensive [[49](#_bookmark97), [12](#_bookmark60)]; thus, it is often costly to acquire sufficient labeled malware data for detection model training. In other words, our built machine learning model for malware detection needs to have the ability to learn from a few samples. To address the data-limited learning challenge, various paradigms have been accordingly proposed, where meta learning [[17](#_bookmark65), [59](#_bookmark107), [63](#_bookmark111)] and transfer learning [[41](#_bookmark89), [40](#_bookmark88)] are some major solutions.

Meta Learning: Meta learning, also known as ”learning to learn,” is a type of machine learning that involves learning how to learn new tasks quickly and efficiently [[22](#_bookmark70)]. It is based on the idea that a learning system can improve its learning ability by learning from past learning experiences. In meta learning, a model is trained on a set of related tasks, to learn how to learn new tasks within the same domain more quickly and effectively. The model is then tested on a new, unseen task and evaluated on its ability to learn and adapt to this task. Meta learning has been applied to a variety of domains, including natural

language processing, computer vision, and reinforcement learning [[23](#_bookmark71)]. It has the potential to enable machine learning systems to learn more efficiently and adapt more quickly to new environments, making it an important area of research in the field of artificial intelligence. However, meta learning has several limitations. Meta learning algorithms can be com-

plex and computationally intensive, which can limit their practicality for certain applica- tions. It is often sensitive to the quality of the training data, and may not perform well if the training data is noisy or biased [[57](#_bookmark105)]. These algorithms may struggle to generalize to tasks that are significantly different from those seen during training, due to a lack of sufficient inductive bias. The most significant limitation to meta learning is that the classes used for meta-training and meta-testing need to be disjoint, but the data are generally collected from the similar problem domain [[25](#_bookmark73)], which, however, is infeasible in few-shot malware detection, since annotations for any malware class are difficult and it is hard to collect such a distribution of malware detection tasks to learn a shared initialization.

Transfer Learning: Transfer learning is a machine learning technique in which a model trained on one task is re-purposed on a second related task. It involves the transfer of knowledge from a source task to a target task, to improve the performance of the model on the target task [[39](#_bookmark87)], which is useful in situations where it is difficult to collect sufficient data for training a model on a new task, or when there is a need to use a pre-trained model as a starting point for a new task. By using transfer learning, it is possible to leverage the knowledge gained from a related task to improve the performance of a model on a new task,

without the need to start from scratch. There are several ways to perform transfer learning, including fine-tuning a pre-trained model, using a pre-trained model as a feature extractor, or using a pre-trained model as a fixed feature extractor [[52](#_bookmark100)]. As such, transfer learning has been applied to a variety of domains, including natural language processing [[43](#_bookmark91)], computer vision [[20](#_bookmark68)], and speech recognition [[46](#_bookmark94)].

However, transfer learning also has certain limitations. First, transfer learning is only effective when the source and target domains are similar enough that knowledge learned in the source domain applies to the target domain. If the domains are too different, transfer learning may not be effective. Second, it can be sensitive to the choice of the source domain and the model pre-trained on that domain, and may not always achieve the best performance compared to training a model from scratch on the target domain [[52](#_bookmark100)]. Third, it still requires a large amount of labeled data in the source domain, which may not always be available or may be difficult to obtain. In this way, transfer learning may not be a good solution to address few-shot malware detection either, since we do not have the large labeled samples for the model fine-tuning.

# Contribution

Similar to transfer learning, adversarial reprogramming is a machine learning technique that involves altering the behavior of a machine learning model by making small, carefully

chosen changes to the input data that the model processes. These changes, known as ad- versarial perturbations, are designed to cause the model to produce a desired output, even if the original input data would have resulted in a different output [[13](#_bookmark61)]. That is, adversarial reprogramming can achieve the same objective as transfer learning that re-purposes a ma- chine learning model pre-trained in a source domain to perform a target-domain task. By contrast, adversarial reprogramming yields an additional advantage that transfer learning does not have: adversarial reprogramming only learns a universal perturbation to be added to the input data, but the pre-trained model, with respect to structure and parameters, keeps unchanged. In this respect, adversarial reprogramming needs much less labeled data sam- ples for model training and deals much better with few-shot machine learning application scenarios [[10](#_bookmark58), [11](#_bookmark59)].

With this in mind, to mitigate the limitations of meta learning and transfer learning, in this thesis, we propose to use adversarial reprogramming to deal with small labeled data for malware detection. More specifically, we present a novel adversarial reprogramming approach to detect malware in a few-shot setting, where we have only a small number of examples of malware and benign files to work with.

Our approach is to reprogram an ImageNet classification neural network to perform few-shot malware detection. Specifically, the model first obtains a set of features from data samples, injects these features into a host image randomly selected from ImageNet, and then adds a universal perturbation to the host image to create a set of new image inputs to represent the original data samples. After that, the adversarial reprogramming model will randomly select two ImageNet classes to indicate malware and benign classes for mal- ware detection. At the end of model formulation, an optimization problem is constructed between the predictions and true labels to minimize the loss function to calculate the op- timal perturbation. The reasons why we choose ImageNet classification neural networks in our proposed adversarial reprogramming model are that these pre-trained models have very deep and non-linear structures, which can cope better with feature learning and im-

prove the malware detection capability, and these neural networks are easily feasible. We evaluate our approach with different ImageNet classification neural networks and differ- ent parameter settings and compare it with different baseline models to demonstrate that it can outperform state-of-the-art few-shot learning methods for malware detection. We can summarize our contributions as follows:

* + - We deal with few-shot malware detection with small labeled data instead of regular data settings with a large number of labeled data.
    - We propose a novel adversarial reprogramming idea to implement this few-shot mal- ware detection model.
    - We evaluate our approach with different ImageNet classification neural networks and different parameter settings, and compare with different baseline models.

# Organization

In this thesis, section [1](#_bookmark0) refers to the background, motivation, and contribution to the thesis. In section [2](#_bookmark6), I explained the related works for few-shot malware detection that have been proposed and the introduction of adversarial reprogramming. In section [3](#_bookmark16), I explained more about adversarial reprogramming technically, how it works, and the difference between adversarial reprogramming and other few-shot models. In section [4](#_bookmark24), I explained how I implemented the model and the parameters with other settings. Then I evaluated the model with different pre-trained ImageNet classification models and with different train data sizes and different parameter values and compared it with the baseline models; random forest and neural network and transfer learning.

**Literature Review**

In this chapter, we would like to introduce the related works, including machine learning- based malware detection models, few-shot learning models, and few-shot malware detec- tion models. Based on this literature review, we can better understand the challenges of malware detection and the differences between our proposed few-shot malware detection from the current works.

# Malware Detection

Malware detection is the process of identifying and mitigating the presence of malware on a computer system or network. This can be done through a variety of means, including the use of antivirus software, manual inspection of system files and processes, and the use of machine learning algorithms [[21](#_bookmark69)]. In this section, we would like to present different machine learning detection methods.

## Signature-based Malware detection

Signature-based methods are generally employed in anti-malware software products from different security companies to provide the major protections against malware attacks [[16](#_bookmark64)]. A signature is a specific pattern or characteristic that is unique to a particular type of mal- ware [[5](#_bookmark53)]. We can easily find some research papers that use signature-based methods for

malware detection. Deepak et al. performed malware detection on mobile devices using a signature-based malware detection method [[56](#_bookmark104)]. Abbas et al. built a low complexity signature-based method for IoT devices that only identifies and stores a subset of signa- tures to detect a group of malware instead of storing a separate signature for every potential malware [[1](#_bookmark49)]. Savenko et al. proposed a method for signature generation of malware based on API call tracing [[45](#_bookmark93)]. But the limitation of signature-based malware detection lies in the fact that they are effective at detecting known malware, but they can be less effective at detecting new or unknown types of malware; also, these models can be easily get evaded by malware attacks using more sophisticated techniques, such as obfuscation, and also a large amount of malware generated every data.

## Behavior-based Malware detection

To address the limitation of signature-based malware detection, another approach is pro- posed to use behavior-based information, which involves analyzing the behavior of a pro- gram or process to determine whether it is exhibiting characteristics that are indicative of malware [[5](#_bookmark53)]. Burguera et al. built a malware detection model using dynamic analysis of application behaviors in android [[7](#_bookmark55)], Liu et al. implemented a model using Malware Be- havior Feature (MBF) based malware detection algorithm [[31](#_bookmark79)]. This approach can be more effective at detecting new or unknown types of malware, but it can also be more resource- intensive and may produce more false positives.

## Machine learning-based Malware detection

In recent years, machine learning has become a popular approach for detecting malware, as it allows models to learn and adapt to new types of malware over time. The advantages of machine learning algorithms are that they can analyze large datasets of known malware and benign software to identify patterns and features that are indicative of malware, and

can then be used to classify new, unseen software as either benign or malicious.

There has been a significant amount of research using machine-learning techniques for malware detection. One common approach is to use traditional machine learning algo- rithms, such as decision trees [[67](#_bookmark115)], support vector machines [[28](#_bookmark76)], and ensemble learning [[64](#_bookmark112)], to classify executables as benign or malicious based on static features extracted from the executables. These static features may include characteristics of the executable file it- self, such as its size, entropy, and the presence of certain strings or patterns [[42](#_bookmark90), [15](#_bookmark63)]. For example, Zulkifli et al. implemented a model based on network traffic using decision tree algorithm [[67](#_bookmark115)]. Zhao et al. proposed a behavior-based malware detection model using sup- port vector machine algorithm [[65](#_bookmark113)]. Azzez et al. presented a malware detection method based on ensemble learning. A stacked ensemble of fully-connected, one-dimensional con- volutional neural networks (CNNs) performs the base-stage classification, while a machine learning algorithm performs the end-stage classification [[4](#_bookmark52)].

In recent years, there has been a growing trend toward using deep learning techniques for malware detection. These techniques, such as convolutional neural networks (CNNs)

1. and long short-term memory (LSTM) [[62](#_bookmark110)] networks, are able to learn more complex patterns in the data and have achieved state-of-the-art results on many tasks. Deep learning approaches for malware detection often use dynamic features extracted from the execution of the executable, such as the system calls made by the executable or the network traffic generated by the executable [[19](#_bookmark67), [2](#_bookmark50)]. For example, Ganesh et al. suggested a technique, that utilizes a convolutional neural network to evaluate authorization patterns [[18](#_bookmark66)]. Based on behavioral data, McDole et al. carried out malware detection using process-level perfor- mance metrics, such as consumption of CPU, memory, and disk with convolutional neural network (CNN). [[33](#_bookmark81)]. Vinayakumar et al. used the long short-term memory (LSTM) archi- tecture for Android malware detection [[58](#_bookmark106)].

Overall, machine learning can be a powerful tool for detecting malware, but it is im- portant to carefully consider the type of machine learning approach and the dataset being

used, as these factors can significantly impact the accuracy and effectiveness of the model. There are several limitations to using machine learning for malware detection [[24](#_bookmark72)], which are summarized as follows:

* + Need for large, high-quality datasets. Machine learning algorithms require large datasets of known malware and benign software in order to learn and classify new, unseen software. If the dataset is small or of low quality, the model may not be able to accurately classify new software.
  + Vulnerability to adversarial examples. Machine learning models can be vulnerable to adversarial examples, which are intentionally misclassified examples designed to trick the model into making incorrect predictions. This can be a concern in the con- text of malware detection, as attackers may try to create adversarial examples of malware in order to evade detection by the model.
  + Need for ongoing training and evaluation. Machine learning models require ongoing training and evaluation to maintain their accuracy and effectiveness. If the model is not regularly updated and tested, it may become less effective at detecting malware over time.
  + Limited ability to detect new or unknown types of malware. Machine learning al- gorithms are generally more effective at detecting known types of malware, as they are trained on specific patterns and features that are indicative of malware. How- ever, they may be less effective at detecting new or unknown types of malware, as they have not been trained on these types of malware and may not recognize them as malicious.

In this thesis, we mainly focus on solving the limitation of machine learning-based malware detection with limited labeled data samples, and investigating how we can build a few-shot malware detection model to improve the detection performance.

# Few-Shot Learning

As we would like to build a few-shot malware detection model, in this section, we list some major few-shot learning techniques to facilitate understanding data limitation and constructing our few-shot malware detection model. Few-shot learning is a machine learn- ing technique that involves learning to perform a new task using only a small number of examples. This is an important problem in the context of not just malware detection but also any other cyber security attack detection, as it is often costly or time-consuming to obtain large amounts of labeled data for these types of detection tasks [[57](#_bookmark105)]. Some major few-shot learning methods with their own unique set of benefits and drawbacks are introduced in detail as follows.

## Meta Learning

Meta learning is a type of machine learning that involves learning how to learn. In the context of malware detection, a meta-learning approach could involve training a model to learn how to classify new, previously unseen examples of malware by adapting its learning strategy based on the examples it has seen so far [[23](#_bookmark71), [66](#_bookmark114)]. There are several approaches to perform meta learning, including:

* + - * Model-based meta learning: This approach involves training a neural net- work to learn a task by learning a model of the task. The model is then used to make predictions about the task, which can be used to improve the model’s performance [[50](#_bookmark98)].
      * Optimization-based meta learning: This approach involves training a model to optimize its own parameters, based on its experience with previous tasks. The model learns to optimize its own learning process, rather than learning the task directly [[22](#_bookmark70), [60](#_bookmark108)].
      * Memory-based meta learning: This approach involves training a model to use its memory of previous tasks to learn new tasks more efficiently. The model stores information about past tasks in its memory and uses this information to guide its learning process for new tasks [[60](#_bookmark108)].

Meta learning has a wide range of potential applications, including natural language processing [[27](#_bookmark75)], computer vision [[35](#_bookmark83)], and robotics [[26](#_bookmark74)]. However, like any machine learn- ing approach, it has certain limitations that should be considered. Some of the limitations of meta learning include [[22](#_bookmark70)]:

* + - * Data requirements: Meta learning often requires a large amount of data in order to learn effectively. This can be a challenge in situations where it is difficult to collect sufficient data for training a model on a specific task.
      * Limited generalization: Meta learning algorithms are typically designed to work well on a specific set of related tasks, but may not generalize well to tasks outside of this domain.
      * Sensitivity to hyper-parameters: Meta learning algorithms can be sensitive to the choice of hyper-parameters, which can make it difficult to fine-tune the model for a specific task.

## Transfer Learning

Transfer learning is a type of machine learning that involves using knowledge learned from one task to improve the performance of a model on a related task [[39](#_bookmark87), [44](#_bookmark92)]. The goal of trans- fer learning is to leverage the knowledge and experience gained from solving one problem to improve the performance of a model on a different, but related problem. For example, imagine that you have trained a deep-learning model to classify images of dogs and cats. If you wanted to use this model to classify images of birds, you could use transfer learning

by fine-tuning the model on a dataset of bird images. This would allow you to leverage the knowledge the model has already gained about image recognition and classification and fine-tune it to perform the specific task of bird classification [[52](#_bookmark100)].

Transfer learning can be a powerful tool in machine learning because it allows you to build on the work of others and take advantage of pre-trained models that have already been trained on large, high-quality datasets. This can save time and resources, and can often lead to better performance than training a model from scratch. There are several approaches to perform transfer learning, including fine-tuning [[39](#_bookmark87)], feature extraction [[52](#_bookmark100)], and multi- task learning [[44](#_bookmark92)]. Each approach involves using a pre-trained model as a starting point and adjusting it to perform a new task, with the specific approach depending on the details of the new task and the availability of data.

However, it has certain limitations that should be considered. Some of the limitations of transfer learning include [[52](#_bookmark100)]:

* + - * Limited to related tasks: Transfer learning is most effective when the source and tar- get tasks are closely related. If the tasks are too dissimilar, the knowledge learned from the source task may not be useful for the target task, resulting in poor perfor- mance.
      * Lack of generalization: Transfer learning algorithms are typically designed to work well on a specific set of related tasks, but may not generalize well to tasks outside of this domain.
      * Dependence on the quality of the pre-trained model: The performance of a transfer learning model is dependent on the quality of the pre-trained model. If the pre-trained model is not well-suited for the target task, the performance of the transfer learning model may be poor.

## Other Techniques

In addition to meta-learning and transfer learning, there have also been efforts to design more effective feature representations and similarity measures for few-shot learning. These approaches aim to capture the important characteristics of input samples and measure the similarity between different types of samples in a way that is robust to variations in the input data [[53](#_bookmark101)].

# Few-shot Malware Detection

Some approaches have been designed and developed to address few-shot malware detection using the aforementioned techniques, including transfer learning [[44](#_bookmark92)], and meta learning [[27](#_bookmark75)]. Transfer learning involves fine-tuning a pre-trained machine learning model on a mal- ware detection task using a small amount of labeled data. Meta learning involves training a machine learning model to adapt to new malware detection tasks using a small amount of labeled data [[53](#_bookmark101)]. For example, Martin et al. proposed a model using meta-information from the Android Manifest to analyze and find fraudulent Android applications; its major goal is to offer a quick but accurate tool that can help users prevent infecting their devices without even needing to install the application to carry out the examination [[32](#_bookmark80)]. To more accurately capture the characteristics of the studied segments, Tahan et al. implemented the model employing a novel feature type called a meta-feature [[51](#_bookmark99)]. Bhodia et al. dealt with the issue of malware categorization and detection using image analysis. Bhodia et al. used deep learning (DL) models to apply image recognition after converting executable files to images [[6](#_bookmark54)]. Chen et al. proposed a model using computer vision’s deep transfer learning to categorize static malware and apply knowledge from naturally occurring images or objects to the target domain of static malware detection in the transfer learning scheme [[9](#_bookmark57)].

**Design of Few-Shot Malware Detection**

Few-shot malware detection is to train a machine learning model to classify new, unseen types of malware based on a small number of examples, or “shots” [[8](#_bookmark56)]. As traditional machine learning approaches may require a larger dataset for model training [[54](#_bookmark102)], this ap- proach is particularly useful in situations where there are few examples of a particular type of malware available for training [[21](#_bookmark69)]. In this chapter, we are using adversarial repro- gramming to build a few-shot malware detection model. As the adversarial reprogramming technique uses machine learning vulnerability as a fundamental for the design to transfer the input with perturbation and change the output that leads to re-purposing the model for other tasks, we first explain adversarial vulnerability more technically and then dive into the technical steps in detail for our design for few-shot malware detection.

# Adversarial Vulnerability

Adversarial vulnerability in machine learning refers to the susceptibility of a machine learn- ing model to being deceived or fooled by malicious or unintended inputs [[48](#_bookmark96)]. These inputs, called adversarial examples, have been specifically crafted to cause the model to make mis- takes or incorrect predictions, which can be in the form of images, texts, or other types of data and designed to be similar to normal, legitimate inputs but with subtle differences that can be difficult for humans to detect [[14](#_bookmark62)].

One example of such an adversarial vulnerability is that an attacker crafts an image

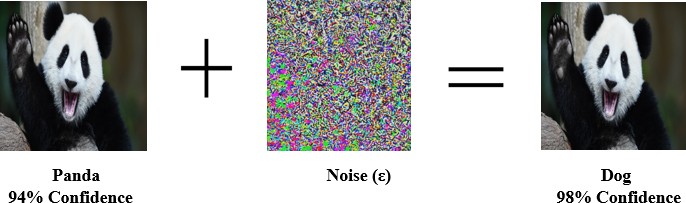


Figure 3.1: An example of adversarial vulnerability

that is intentionally designed to mislead a machine learning model trained for image clas- sification. For instance, consider a model that has been trained to recognize animals in images [[38](#_bookmark86)]. As illustrated in Figure [3.1](#_bookmark18), an attacker could generate an adversarial image of a panda in an easy way that the model incorrectly classifies it as a dog. This could be done, for example, by adding small, imperceptible perturbations to the image that are specifically designed to fool the model [[48](#_bookmark96)].

Different from crafting perturbation for individual input, the universal perturbation is a small change added to all inputs that can cause a classifier to misclassify most inputs, which is generally drawn from a given distribution [[36](#_bookmark84)]. The goal is to find a perturbation vector v that satisfies two constraints:

* + - It has a small norm (as measured by the p-norm, with *p* ∈ [1*,* ∞)).

||*v*||*p <*= *ϵ* (3.1)

* + - It causes the classifier to misclassify at least 1-*δ* fraction of inputs drawn from the distribution.

where the parameters *ϵ* and *δ* are used to control the magnitude of the perturbation vector and the desired fooling rate, respectively [[36](#_bookmark84), [48](#_bookmark96)].

Adversarial vulnerability is a concern in machine learning because it can potentially

lead to serious consequences, such as incorrect medical diagnoses or financial fraud. There- fore, it is important for machine learning researchers and practitioners to consider these vulnerabilities when developing and deploying machine learning models. However, these vulnerabilities are also good opportunities to be applied for social good. The focus of this thesis is one of such cases, which attempts to craft a universal perturbation to be added to all inputs that can change the behaviors of the pre-trained neural networks, and accordingly reprograms their functions to perform malware detection.

# Adversarial Reprogramming

Inspired by adversarial vulnerability, adversarial reprogramming is proposed to re-purpose a pre-trained model in a source domain to perform a new task in a target domain by adding universal perturbation into the inputs [[37](#_bookmark85)]. Here, we reprogram an ImageNet classification neural network to address few-shot malware detection problem. In more detail, the model first extracts a collection of features from data samples, adds these characteristics to a host image drawn at random from ImageNet, and then adds a universal perturbation to the host image to produce a set of new image inputs that reflect the original data samples. Next, two ImageNet classes will be randomly chosen using the adversarial reprogramming model to represent malware and benign classes for malware detection. The best perturbation is determined by minimizing the loss function after the model construction process, which involves creating an optimization problem between the predictions and true labels. The advantages yielded by adversarial reprogramming are [[11](#_bookmark59)]:

* + - Only the perturbation is trainable and requires less training time and labeled data than transfer learning and other models that are created from scratch.
    - The ImageNet model can be used for a range of malware detection tasks without modifying the model’s structure or computations because software features must al- ways be converted to images due to the model’s fixed input format.

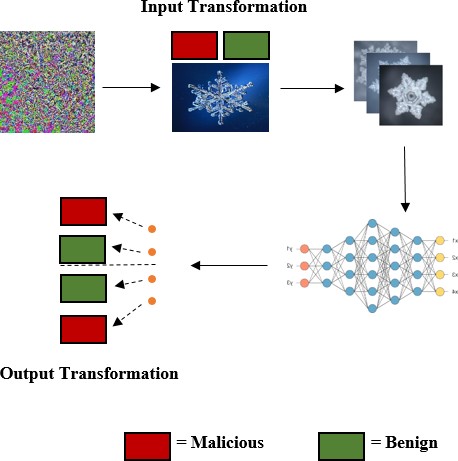


Figure 3.2: Overview of the designed adversarial reprogramming model

* + - With the help of pre-trained weights and layers on ImageNet neural networks, it is possible to identify expressive patterns from subtle software features and perform well at malware detection.

Based on the aforementioned advantages of adversarial reprogramming, to deal with machine learning-based malware detection with few labeled data samples, we build a novel adversarial reprogramming model based on a pre-trained ImageNet classification neural network, which is illustrated in Figure [3.2](#_bookmark20). Overall, our adversarial reprogramming model proceeds with three steps: (1) input transformation, (2) output transformation, and (3) op- timization. This leads to three major goals:

* + - Input transformation to embed the software features with the perturbation into the host image to create new image data.
    - Output transformation to map the ImageNet classes to malware detection classes.
    - Optimization to obtain the optimal perturbation.

We detail all these three major steps as follows.

## Input Transformation

To perform input transformation, there were two important steps. One is software feature embedding and the other is applying perturbation. For feature embedding, I assigned fea- tures of my dataset to a Numpy array and embedded them to randomly selected pixels of the host image and stored the index values of the pixels so that it can generate a whole new image dataset for training and testing. After feature embedding, I added a universal perturbation function to all the inputs. I also introduced a parameter epsilon *ϵ*, to analyze the magnitude of the perturbation [[13](#_bookmark61), [10](#_bookmark58)]. The perturbation function is formulated to be added to all inputs, which can be defined as:

*θ*˜ = *ϵ* · *tanh*(*θ* ⊙ *M* ) (3.2)

where *θ* ∈ R*n*×*n*×3 refers to perturbation, *M* is the matrix of mask values to specify the pixels used to store the software features, ⊙ refers to element-wise product, tanh (·) sets the bounds of the perturbation to be in ( -1,1) . To control the amount of the perturbation, we introduce an adjustable hyper-parameter *ϵ*. The transformed new input data sample can thus be presented as a transformation function *hs*(*x*; *θ*) defined as follows:

*hs*(*x*; *θ*) = *X*˜ = *clip*(*X* + *ϵ* · *tanh*(*θ* ⊙ *M* )) (3.3)

where *X* is input data in a format of host image with feature embedding *x*, clip ( ·) limits the values of each pixel in the image by clipping them to a specified range ( 0,1) and *X*˜

represents the new image input after input transformation. In our scenario, both *ϵ* and clip ( ·) result in the perturbation imperceptibility.

## Output Transformation

The goal of the output transformation process is to map the output classes of the ImageNet classification neural network back to the classes used for malware detection (i.e., benign and malicious). To do this, we implement a hard-coded mapping to perform this operation for detection [[47](#_bookmark95)].

More specifically, the hard-coded mapping involves simply assigning two randomly- selected class outputs out of 1,000 ImageNet classes to predict benign and malicious classes, respectively. This is done by using a function *ht*(·) that takes an output *y*˜ of the ImageNet model and maps it to a pair of classes *yi* and *yj*, where i is not equal to j.

*ht*(*y*˜) = ⟨*y*˜*i, y*˜*j*⟩*, i*

*j.* (3.4)

Overall, the output transformation process is an important step in adversarial repro- gramming, as it allows the results of the ImageNet model to be translated into the classes used for malware detection [[12](#_bookmark60)].

## Optimization

To develop a cost-efficient method for detecting malware, the pre-trained ImageNet classi- fication neural network needs to be self-deployed for complete access, such that no addi- tional expenses on large model queries will be incurred and we can perform gradient-based method to optimize the adversarial reprogramming model and obtain the ideal perturbation.

In this respect, the optimization of our adversarial reprogramming model is formulated as an optimization problem where the goal is to minimize a loss function that takes into ac- count the difference between the probability that an input image, transformed from soft- ware, will be classified as malware and its ground-truth label, where a regularization term is added to help prevent overfitting [[11](#_bookmark59)]. The adversarial reprogramming model optimization can be formally written out as:

*θ*∗ = argmin (−log(*p*(*ht*(*y*˜)|*hs*(*x*; *θ*))) + *λ*||*θ*||2*F* ) (3.5)

where *λ* is a regularization parameter, and *p*(*ht*(*y*˜)|*hs*(*x*; *θ*)) shows the likelihood that an image input *X* that was altered by features *x* will be categorized as *y*˜, which can be mapped to malware. The single parameter of the problem, *θ*, is updated using Adam, an optimiza- tion algorithm that makes use of first and second-moment estimates of the gradient to adapt the learning rate. The optimization problem described in this subsection is a key component of the adversarial model, which is critical for achieving the goal of cost-efficient malware detection using self-deployed ImageNet classification neural networks.

**Experimental Results and Analysis**

In this chapter, we evaluate the effectiveness of our proposed few-shot malware detection model over a real malware dataset. First, we introduce the dataset in detail and then spec- ify the experimental settings. After that, we evaluate the impacts of different pre-trained models, parameters, and data sizes, and also compare with some baselines to demonstrate the advantages yielded by our adversarial reprogramming model.

# Experiment Setup

## Dataset

For this experiment, I used the MalData dataset from the GitHub open source repository[1](#_bookmark27). This dataset consists of 138,047 entries, with 41,323 benign files and 96,724 malware files. The data statistics are illustrated in Table [4.1](#_bookmark28). Each file in the dataset is characterized by 56 features, including the number of resources, the size of initialized data, the size of uninitialized data, the major and minor linker versions, the MD5 hash, the size of code, the machine type, the size of the optional header, and the characteristics. These features provide a wealth of information about each file, allowing for thorough analysis and com- parison. Considering that the feature scales are very different, we normalize these feature values before embedding them into the host image. The MalData dataset is a valuable

1https://github.com/PacktPublishing/Mastering-Machine-Learning-for-Penetration-Testing

Table 4.1: Statistics of the dataset used in this thesis

**Dataset No. of Entries No. of Benigns No. of Malwares No. of Features**

MalData 138,047 41,323 96,724 56

resource for researchers studying malware and seeking to develop effective methods for detecting and mitigating its effects.

The dataset includes the following features, where the detailed feature value examples are given in Table [4.2](#_bookmark29):

* + - * Name is the name of the file.
      * md5 is the MD5 hash of the file, which is a unique identification code that can be used to verify the integrity of the file.
      * Machine is the machine type the file is intended to run on, such as x86 or x64.
      * SizeOfOptionalHeader is the size of the optional header in the file, which contains information about the file’s layout and execution.
      * Characteristics is a set of flags indicating the characteristics of the file, such as whether it is a dynamic-link library (DLL) or whether it is intended to be run on a system with high entropic content.
      * MajorLinkerVersion and MinorLinkerVersion are the major and minor version numbers of the linker used to create the file. The linker is a program that combines object files and libraries to create an executable file.
      * SizeOfCode is the size of the code section in the file, which contains the instruc- tions that the processor will execute.
      * SizeOfInitializedData is the size of the initialized data section in the file, which contains data that is initialized when the file is loaded into memory.

Table 4.2: Features of files from dataset

|  |  |  |
| --- | --- | --- |
|  | **0** | **2** |
| **Name** | mshtml.dll | VirusShare cf329dab9d0e2b9129b27771a2862394 |
| **md5** | d20f7eea01f00190902462c0b69ec6c8 | cf329dab9d0e2b9129b27771a2862394 |
| **Machine** | 34404 | 332 |
| **SizeOfOptionalHeader** | 240 | 224 |
| **Characteristics** | 8226 | 783 |
| **MajorLinkerVersion** | 9 | 2 |
| **MinorLinkerVersion** | 0 | 56 |
| **SizeOfCode** | 6752256 | 29184 |
| **SizeOfInitializedData** | 2310656 | 14848 |
| **SizeOfUninitializedData** | 0 | 110592 |
| **AddressOfEntryPoint** | 21520 | 14764 |
| **BaseOfCode** | 4096 | 4096 |
| **BaseOfData** | 0 | 36864 |
| **ImageBase** | 8793907789824.0 | 4194304.0 |
| **SectionAlignment** | 4096 | 4096 |
| **FileAlignment** | 512 | 512 |
| **MajorOperatingSystemVersion** | 6 | 4 |
| **MinorOperatingSystemVersion** | 1 | 0 |
| **MajorImageVersion** | 6 | 6 |
| **MinorImageVersion** | 1 | 0 |
| **MajorSubsystemVersion** | 5 | 4 |
| **MinorSubsystemVersion** | 2 | 0 |
| **SizeOfImage** | 9076736 | 221184 |
| **SizeOfHeaders** | 1536 | 1024 |
| **CheckSum** | 9120035 | 0 |
| **Subsystem** | 2 | 2 |
| **DllCharacteristics** | 64 | 32768 |
| **SizeOfStackReserve** | 262144 | 2097152 |
| **SizeOfStackCommit** | 4096 | 4096 |
| **SizeOfHeapReserve** | 1048576 | 1048576 |
| **SizeOfHeapCommit** | 4096 | 4096 |
| **LoaderFlags** | 0 | 0 |
| **NumberOfRvaAndSizes** | 16 | 16 |
| **SectionsNb** | 6 | 7 |
| **SectionsMeanEntropy** | 5.41745943392 | 3.34528001443 |
| **SectionsMinEntropy** | 2.76177448394 | 0.0 |
| **SectionsMaxEntropy** | 6.76452138512 | 6.30323831549 |
| **SectionsMeanRawsize** | 1509290.66667 | 8118.85714286 |
| **SectionsMinRawsize** | 53760 | 0 |
| **SectionMaxRawsize** | 6752256 | 29184 |
| **SectionsMeanVirtualsize** | 1510175.16667 | 28755.4285714 |
| **SectionsMinVirtualsize** | 60704 | 140 |
| **SectionMaxVirtualsize** | 6751839 | 110088 |
| **ImportsNbDLL** | 13 | 8 |
| **ImportsNb** | 935 | 155 |
| **ImportsNbOrdinal** | 147 | 0 |
| **ExportNb** | 20 | 0 |
| **ResourcesNb** | 134 | 8 |
| **ResourcesMeanEntropy** | 3.28753758854 | 4.0912689525 |
| **ResourcesMinEntropy** | 1.11239546515 | 2.45849222582 |
| **ResourcesMaxEntropy** | 7.99092475232 | 5.86996923095 |
| **ResourcesMeanSize** | 1965.05223881 | 2088.75 |
| **ResourcesMinSize** | 20 | 48 |
| **ResourcesMaxSize** | 67585 | 9640 |
| **LoadConfigurationSize** | 0 | 0 |
| **VersionInformationSize** | 17 | 0 |
| **legitimate** | 1 | 0 |

* + - * SizeOfUninitializedData is the size of the uninitialized data section in the file, which contains data that is not initialized when the file is loaded into memory.
      * AddressOfEntryPoint is the address of the entry point of the file, which is the location in memory where the execution of the file begins.
      * BaseOfCode is the base address of the code section in the file, which is the starting address of the code section when the file is loaded into memory.
      * BaseOfData is the base address of the data section in the file, which is the starting address of the data section when the file is loaded into memory.
      * ImageBase is the preferred address of the first byte of the file when it is loaded into memory.
      * SectionAlignment is the alignment of the sections in the file, which determines how the sections are arranged in memory.
      * FileAlignment is the alignment of the file on disk, which determines how the file is arranged on the disk.
      * MajorOperatingSystemVersion and MinorOperatingSystemVersion are the major and minor version numbers of the required operating system.
      * MajorImageVersion and MinorImageVersion are the major and minor ver- sion numbers of the image.
      * MajorSubsystemVersion and MinorSubsystemVersion are the major and minor version numbers of the subsystem.
      * SizeOfImage is the size of the image, including all headers, in memory.
      * SizeOfHeaders is the size of the headers in the file.
      * CheckSum is the checksum of the file, which is a value calculated from the contents of the file that can be used to verify the integrity of the file.
      * Subsystem is the subsystem required to run the file, such as a graphical user inter- face (GUI) or a command-line interface (CLI).
      * DllCharacteristics is a set of flags indicating the DLL characteristics of the file, such as whether it is re-locatable or whether it supports high-entropy 64-bit virtual address space.
      * SizeOfStackReserve is the size of the stack to reserve for the file. The stack is a portion of memory used for storing temporary data, such as function parameters and local variables.
      * SizeOfStackCommit is the size of the stack to commit for the file. When a memory page is committed, it is reserved for the program’s use and can be accessed.
      * SizeOfHeapReserve is the size of the heap to reserve for the file. The heap is a portion of memory used for dynamic memory allocation.
      * SizeOfHeapCommit is the size of the heap to commit for the file. When a mem- ory page is committed on the heap, it is reserved for the program’s use and can be accessed.
      * LoaderFlags is a set of flags indicating the state of the file.
      * NumberOfRvaAndSizes is the number of data directories in the file. Data direc- tories contain information about the file’s resources, such as its import and export tables.
      * SectionsNb is the number of sections in the file. A file is divided into sections, each of which has a specific purpose, such as containing code or data.
      * SectionsMeanEntropy is the mean entropy of the sections in the file. Entropy is a measure of the randomness or disorder of a system, and it can be used to assess the complexity of the file’s sections.
      * SectionsMinEntropy is the minimum entropy of the sections in the file.
      * SectionsMaxEntropy is the maximum entropy of the sections in the file.
      * SectionsMeanRawsize is the mean size of the sections in the file.
      * SectionsMinRawsize is the minimum size of the sections in the file.
      * SectionMaxRawsize is the maximum size of the sections in the file.
      * SectionsMeanVirtualsize is the mean virtual size of the sections in the file. The virtual size of a section is the size it occupies in memory, which may be larger than its actual size on disk.
      * SectionsMinVirtualsize is the minimum virtual size of the sections in the file.
      * SectionMaxVirtualsize is the maximum virtual size of the sections in the file.
      * ImportsNbDLL is the number of dynamic-link libraries (DLLs) imported by the file.
      * ImportsNb is the number of imported functions in the file.
      * ImportsNbOrdinal is the number of imported functions with ordinals in the file. An ordinal is a number that identifies a function in a DLL, and it can be used to import the function more quickly than by using its name.
      * ExportNb is the number of exported functions in the file. An exported function is a function that can be called by other programs.
      * ResourcesNb is the number of resources in the file. Resources are data that is stored in the file and can be accessed at runtime, such as images and strings.
      * ResourcesMeanEntropy is the mean entropy of the resources in the file. En- tropy is a measure of the randomness or disorder of a system, and it can be used to assess the complexity of the file’s resources.
      * ResourcesMinEntropy is the minimum entropy of the resources in the file.
      * ResourcesMaxEntropy is the maximum entropy of the resources in the file.
      * ResourcesMeanSize is the mean size of the resources in the file.
      * ResourcesMinSize is the minimum size of the resources in the file.
      * ResourcesMaxSize is the maximum size of the resources in the file.
      * LoadConfigurationSize is the size of the load configuration data in the file. The load configuration data contains information about how the file should be loaded into memory.
      * VersionInformationSize is the size of the version information in the file. The version information contains details about the version of the file, such as its copyright and company name.

## Parameters

In the experiment, several parameters were used to train and test the adversarial repro- gramming model. The train parameters include the number of epochs to train 12, the initial learning rate as 0.01, the batch size as 32, the weight decay as 5e-4, and the epsilon *ϵ* value used for rounding while updating the weights as 0.3. The test parameters include the step size at which weights were updated is set to 4 and the gamma value is 0.9.

## Settings

The settings for the experiment involve using different portions of the training dataset to test the model, ranging in {80%*,* 5%*,* 0*.*1%*,* 0*.*05%*,* 0*.*01%}. The hyper-parameter epsilon is set to a constant value of 0.3, where its impact on the model performance is also analyzed by changing the value of epsilon from 0.1 to 0.5. Four different pre-trained ImageNet Clas- sification models (resnet50, resnet101, densenet121, and densenet161) with pre-trained weights from the PyTorch and Torch-vision modules were used as the basis for the adver- sarial task. The baseline models used for comparison are random forest, neural network, and transfer learning.

# Evaluation

## Impact of Pre-Trained Model

Adversarial reprogramming is a type of attack on machine learning models where an at- tacker attempts to cause the model to perform a task that it was not designed for by adding small, carefully crafted perturbations to the input data [[61](#_bookmark109)]. In this experiment, we tested the effectiveness of this attack on different ImageNet models using a small training dataset and a larger test dataset, while keeping the perturbation constant at *ϵ* = 0.3.

Table 4.3: Evaluation on the impact of pre-trained models

|  |  |  |
| --- | --- | --- |
| **Pre-trained Models** | **Accuracy** | **F1-score** |

|  |  |  |
| --- | --- | --- |
| resnet50 | 97.73 | 96.21 |

|  |  |  |
| --- | --- | --- |
| resnet101 | 97.50 | 95.89 |

|  |  |  |
| --- | --- | --- |
| densenet121 | 98.05 | 96.74 |

densenet161

97.66

96.08

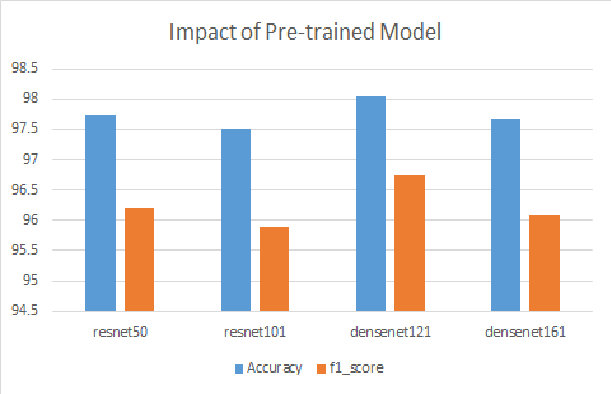


Figure 4.1: Evacuation on the impact of pre-trained model

We conducted an experiment where we tested the performance of adversarial re- programming on four different ImageNet models: resnet50, resnet101, densenet121, and densenet161. We presented the results of the experiment in Figure [4.1](#_bookmark35) and Table [4.3](#_bookmark34), and found that the densenet121 model has the best performance, with an accuracy of more than 98%. This suggests that the densenet121 model was the most resistant to the adversarial reprogramming attack among the four models tested.

## Impact of Data Size

In this experiment, we tested the performance of adversarial reprogramming on a dataset that was split into five different categories based on size. The categories included 80% of the dataset (with 110,437 inputs), 5% of the dataset (with 6,902 inputs), 0.1% of the dataset (with 138 inputs), 0.05% of the dataset (with 69 inputs), and 0.01% of the dataset (with 13 inputs). We kept the perturbation constant at *ϵ* = 0*.*3 throughout the experiment. This experiment is significant because we are testing the performance of adversarial reprogram- ming on very small datasets, which may have different characteristics compared to larger datasets. It would be interesting to see how the size of the dataset affects the performance

of the adversarial reprogramming attack.

Table 4.4: Evaluation on the impact of data size

|  |  |  |
| --- | --- | --- |
| **Data Size** | **Accuracy** | **F1-score** |

|  |  |  |
| --- | --- | --- |
| 80% | 98.10 | 96.87 |

|  |  |  |
| --- | --- | --- |
| 5% | 97.99 | 96.64 |

|  |  |  |
| --- | --- | --- |
| 0.1% | 94.62 | 90.06 |

|  |  |  |
| --- | --- | --- |
| 0.05% | 93.02 | 87.32 |

0.01%

92.08

85.37

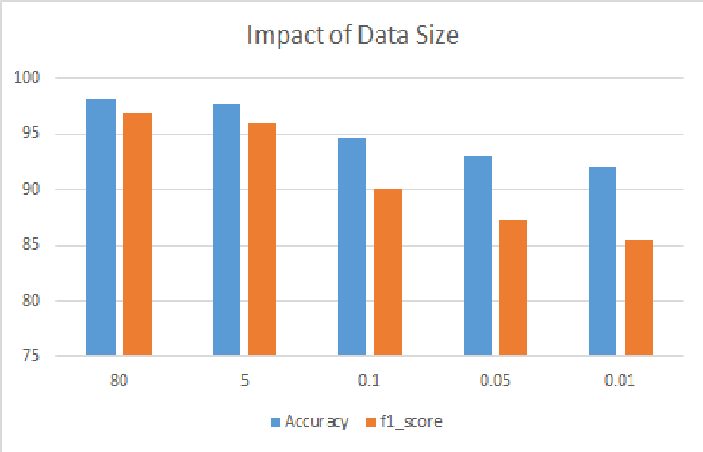


Figure 4.2: Evaluation on the impact of data size

As illustrated in Figure [4.2](#_bookmark38) and Table [4.4](#_bookmark37), we can observe that the attack had a very high efficiency of more than 98% when using 80% of the dataset (with 110,437 inputs) as the training data. We also found that the attack had an accuracy of more than 91% even when using a very small dataset (0.01% of the total dataset, with 13 inputs) as the training data. These results suggest that adversarial reprogramming is a highly effective method that is able to achieve good performance even when using a very small amount of training data, which demonstrate our proposed idea to address few-shot malware detection.

## Impact of Perturbation

In this experiment, we tested the effect of the perturbation function on the performance of adversarial reprogramming. We did this by varying the parameter *ϵ*, which is used to control the magnitude of the perturbations applied to the input data, and observing the performance of the attack with 5% of the dataset as the training data. This is also an interesting experiment because the perturbation function is a key component of adversarial reprogramming, and understanding how it affects the attack can provide insights into how the attack works and how to defend against it. It would be interesting to see how the performance of the attack changes as the value of *ϵ* is varied

Table 4.5: Evaluation on the impact of perturbation magnitude

|  |  |  |
| --- | --- | --- |
| **Perturbation** *ϵ* | **Accuracy** | **F1-score** |

|  |  |  |
| --- | --- | --- |
| 0.1 | 97.60 | 95.98 |

|  |  |  |
| --- | --- | --- |
| 0.2 | 97.80 | 96.34 |

|  |  |  |
| --- | --- | --- |
| 0.3 | 97.99 | 96.64 |

|  |  |  |
| --- | --- | --- |
| 0.4 | 97.66 | 96.45 |

0.5

98.09

97.60

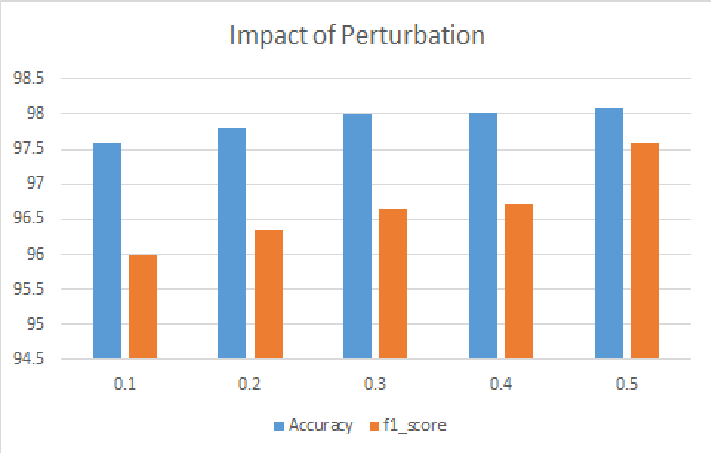


Figure 4.3: Evaluation on the impact of perturbation magnitude

From figure [4.3](#_bookmark41) and table [4.5](#_bookmark40), we can see the experimental results where we tested the performance of adversarial reprogramming with 5% of the dataset as the training data, and varied the parameter *ϵ* ∈ {0*.*1*,* 0*.*2*,* 0*.*3*,* 0*.*4*,* 0*.*5} that controls the magnitude of the perturbations applied to the input data. We recorded the accuracy and f1-score for each value of *ϵ* that we tested. The results show that as the value of *ϵ* increases, the accuracy and f1-score of the attack also generally increase. However, there is a noticeable drop in accuracy and f1-score when *ϵ* is increased from 0.3 to 0.4. This suggests that there may be an optimal value of *ϵ* for this particular dataset that falls in the range between 0.3 and 0.4.

## Comparison with Baselines

In this experiment, we compared the performance of our proposed model with three base- line models (random forest, neural network, and transfer learning) on small data settings. We used three different train datasets with sizes of 0.1%, 0.05%, and 0.01% of the total data samples, and trained all four models on each of these datasets. Here, transfer learning is implemented in a way similar to adversarial reprogramming, with only one difference that transfer learning fine-tunes the parameters for all layers. The goal of the experiment was to see how well each of the models performs on small datasets, and compare the perfor- mance of the proposed model with the baseline models. This is an interesting experiment because it can provide insights into how well these types of models can generalize to small datasets, and whether there are any specific characteristics of the dataset or the models that contribute to their performance. It would be also interesting to see how the performance of the models changes as the size of the train dataset is decreased, and whether there are any notable advantages yielded by the proposed model compared to the baseline models.

As illustrated in Table [4.6](#_bookmark43) and Figure [4.4](#_bookmark44), we can see the comparative results of four different models (random forest, neural network, transfer learning, and adversarial repro- gramming) on a small datasets with sizes of 0.1%, 0.05%, and 0.01% of the total dataset

Table 4.6: Comparison with baselines

Random Forest Neural Network Transfer Learning

Adversarial Reprogramming

F1-score 90.79 87.03 84.12

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Baseline Models** |  | **0.1%** | **0.05%** | **0.01%** |

|  |  |  |  |
| --- | --- | --- | --- |
| Accuracy | 95.10 | 91.33 | 88.92 |

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | F1-score | 92.23 | 82.91 | 80.22 |

|  |  |  |  |
| --- | --- | --- | --- |
| Accuracy | 93.79 | 89.58 | 80.87 |

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | F1-score | 90.43 | 83.70 | 54.09 |

|  |  |  |  |
| --- | --- | --- | --- |
| Accuracy | 91.39 | 86.55 | 64.09 |

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | F1-score | 83.95 | 71.07 | 60.60 |

|  |  |  |  |
| --- | --- | --- | --- |
| Accuracy | 95.62 | 92.81 | 91.59 |

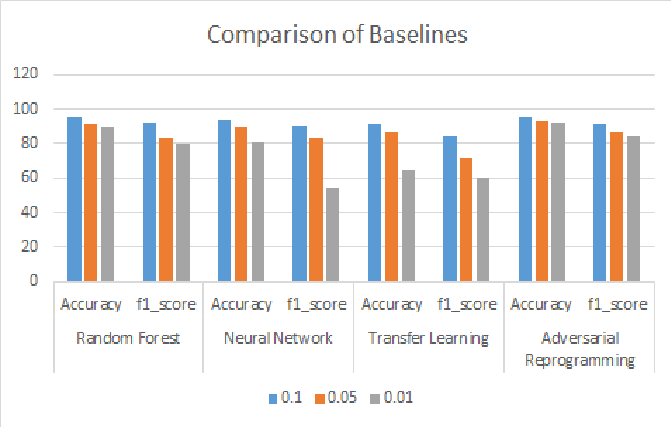


Figure 4.4: Comparison with baselines

in terms of the accuracy and f1-score. The results show that the performance of all four models decreases as the size of the train dataset is decreased. However, the adversarial reprogramming model generally performs better than the baseline models across all train dataset sizes. This suggests that the adversarial reprogramming model may have better gen- eralization performance compared to the other models when working with small datasets.

**Challenges**

One challenge that was faced while building the model for adversarial reprogramming was related to input transformation and embedding features into the host image, as well as saving the indexes of the host image to create a new image dataset. This process can be complex and time-consuming, and can require a lot of trial and error to get right.

Another challenge was finding suitable datasets to use for adversarial reprogramming. we tried using two popular datasets, MNIST and CIFAR10, for adversarial reprogramming, but found that they were not well suited for use with pre-trained models. MNIST is a dataset of gray-scale images of handwritten digits, while CIFAR10 is a dataset of colored images of objects in 10 classes. Both datasets are widely used for machine learning research, but they have some limitations that made them not well suited for use with pre-trained models in this context. One limitation of MNIST is that it has only one channel for gray-scale images, which can limit the types of models that can be used with it. CIFAR10, on the other hand, is a relatively small dataset, which can make it difficult to achieve good performance with more complex models. This highlights the importance of selecting appropriate datasets for a given task, and the challenges that can arise when working with datasets that are not well suited for building a pre-trained model.

In addition to these challenges, adversarial reprogramming can also be computation- ally intensive, particularly when working with large target models or when the perturbations require many iterations to find. This can be a challenge for users with limited computa- tional resources, and may require the use of specialized hardware or techniques to manage

the computational demands of the task. Finally, adversarial reprogramming often involves fine-tuning a pre-trained model on a small number of examples, which can lead to overfit- ting and reduced generalization and accuracy on new and unseen data. This highlights the need to carefully balance the trade-off between model performance and generalization, and to carefully monitor model performance on new data to ensure that it is not overfitting.

**Future Work**

One direction for future work is to explore the effect of different hyper-parameters on the performance of the adversarial reprogramming model. This could involve testing different values for the perturbation parameter epsilon, or trying different optimization algorithms or learning rates. By varying these and other hyper-parameters, it may be possible to find configurations that result in improved performance or faster convergence.

Another direction for future work is to test the model using different pre-trained mod- els as the target model. This could involve using models trained on different datasets or using models with different architectures or hyper-parameters. By comparing the perfor- mance of the adversarial reprogramming model across different target models, it may be possible to identify any characteristics of the target model that affect its vulnerability to the attack or to identify strategies for making the target model more resistant to adversarial reprogramming.

One potential application of adversarial reprogramming is improving machine learn- ing models’ robustness. By altering the behavior of the model in a way that makes it more resistant to noise or perturbations in the input data, it may be possible to improve the gen- eralization performance of the model and make it more robust to changes in the data dis- tribution. This could be an important area of future work, as robustness and generalization are critical concerns in many machine-learning applications.

**Conclusion**

Malware is software that is specifically designed to disrupt, damage, or gain unauthorized access to a computer system. To protect against malware, effective techniques for detecting and mitigating malware are needed. One approach to detecting malware is to use machine learning models, which are algorithms that can learn patterns in data and make predictions or decisions based on those patterns. Machine learning models can be effective for detect- ing malware, but they often require large datasets to achieve good performance. This can be a challenge in the context of malware detection, as the datasets used for training and evaluation are often quite small.

To address this challenge, in this study, we aimed to develop a machine learning model that can achieve good performance even when using small datasets. To do this, we used an adversarial reprogramming technique, which involves modifying the behavior of a pre- trained model by adding small perturbations to the input data. Adversarial reprogramming has been shown to be effective in improving the performance of machine learning models on small datasets.

To test this hypothesis, we compared the performance of the adversarial reprogram- ming model with traditional baseline models on a dataset of malware and benign samples. We found that the adversarial reprogramming model was able to produce efficient results even when using very small datasets, outperforming the traditional baseline models. We also evaluated the performance of the adversarial reprogramming model with different pre- trained ImageNet classification models, with different parameter settings, and with differ-

ent data sizes.

Overall, the results of this study suggest that adversarial reprogramming is a promising approach for improving the performance of machine learning models on small datasets, and could be a valuable tool for improving malware detection in situations where the available datasets are limited. It would be interesting to see how the approach performs on other types of small datasets, and whether it is generally applicable to a wide range of machine learning tasks.

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